## Dagstuhl, July 8-10, 2002:

## MPC, Dagstuhl

July, 2002 $\qquad$ i

## Eternity Variables

to Simulate Specifications
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## Aim of the talk

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How to prove that program $K$ simulates specification $L$ ?
Programs are (executable) specifications
Four kinds of simulations:
functional, forward, backward, eternity
Theorem. Every simulation $F: K \rightarrow L$
that preserves quiescence,
is provable by means of these special ones
A variation of theory of
Abadi and Lamport (1991)
www.cs.rug.nl/~wim/pub/whh275.pdf

## Overview

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1. Temporal Logic of Actions
2. Refinement mappings and simulations between specs
3. Forward and backward simulations
4. Eternity variables
5. Preservation of quiescence and Completeness

## 1. Temporal Logic

 of Actions $\qquad$ ivA specification is a 4 -tuple $K$ :
$X=\operatorname{states}(K)$ : the state space
$Y=\operatorname{init}(K) \subseteq X$ : set of initial states
$N=\operatorname{step}(K) \subseteq X^{2}:$ next-state relation
$P=\operatorname{prop}(K) \subseteq X^{\omega}:$ (fairness) property
An execution is a list xs of states
with $\left(\mathrm{xs}_{i}, \mathrm{Xs}_{i+1}\right) \in N$ for all $i$

- initial iff $\mathrm{xs}_{0} \in Y$.
- a behaviour iff infinite and belongs to $P$
$\operatorname{Beh}(K)=\llbracket Y \rrbracket \cap \square \llbracket N \rrbracket \cap P$
To allow stuttering $N$ is reflexive (and $P$ is a "property").


## Example

$\qquad$ v

Specification LO

```
var k: Int := 0 ;
do k = 0 -> choose k in Int ;
[] true -> k := k - 2 ;
od ;
prop: infinitely often k = 0.
states(LO) = Int
init(LO) ={0}
prop(L0)}=\square\diamond\llbracket\textrm{k}=0
step(LO) =
```



Every state is reachable
The occurring states have k natural and even

## 2. Refinement Mappings

When does spec $K$ implement spec $L$ ?
$K$ : the concrete program
$L$ : the abstract program
A refinement mapping from $K$ to $L$ is
a function $f: \operatorname{states}(K) \rightarrow \operatorname{states}(L)$ such that

$$
\begin{aligned}
& x \in \operatorname{init}(K) \Rightarrow \\
& \left(x, x^{\prime}\right) \in \operatorname{step}(K) \quad \Rightarrow(x) \in \operatorname{init}(L) \\
& x s \in \operatorname{Beh}(K) \Rightarrow \\
& \Rightarrow \\
& \left.f^{\omega}(x s) \in \operatorname{Beh}(x), f\left(x^{\prime}\right)\right) \in \operatorname{step}(L)
\end{aligned}
$$

## Example $K(m)$

for $m>1$
var $\mathrm{j}:$ Nat: $=0$;
do true $\rightarrow \mathrm{j}:=(\mathrm{j}+1) \bmod m$ od ;
prop: j changes infinitely often.
$\operatorname{states}(K(m))=\mathbb{N}$
$\operatorname{init}(K(m))=\{0\}$
$\operatorname{prop}(K(m))=\square \diamond \llbracket \neq \rrbracket$
$\left(j, j^{\prime}\right) \in \operatorname{step}(K(m)) \equiv j^{\prime} \in\{j,(j+1) \bmod m\}$

A refinement mapping $f$ from $K(21)$ to $K(14)$ ?
Take $f: \mathbb{N} \rightarrow \mathbb{N}$ with $f(j)=\min (j, 13)$
The abstract behaviour stutters
whenever the concrete behaviour proceeds from 13 to 20
vii.1. - Refinement mappings are not enough.

We sometimes need simulations

## Simulations (new)

$\qquad$ viii
Spec $K$ simulates spec $L$
via relation $F \subseteq \operatorname{states}(K) \times \operatorname{states}(L)$
(notation $F: K \rightarrow L$ )
三
for every xs $\in \operatorname{Beh}(K)$
there is ys $\in \operatorname{Beh}(L)$
with $\left(\mathrm{xs}_{n}, y s_{n}\right) \in F$ for all $n$
Every refinement mapping
$f: \operatorname{states}(K) \rightarrow \operatorname{states}(L)$
induces a simulation $K \rightarrow L$
If $F: K \rightarrow L$ and $F \subseteq G$
then $G: K \rightarrow L$
The smaller the simulation, the more information it carries

## Example

with prescience $\qquad$ ix
$K$ and $L$
both with state space $X=\{0,1,2,3,4\}$,
initial set $\{4\}$, and property $\diamond \llbracket\{0,1\} \rrbracket$.
$\operatorname{step}(K)=1_{X} \cup\{(4,2),(2,1),(2,0)\}$
$\operatorname{step}(L)=1_{X} \cup\{(4,3),(4,2),(3,1),(2,0)\}$



Simulation $F=1_{X} \cup\{(2,3)\}$
Concrete state 2 splits
into abstract states 2 and 3

## Visibility

 xVisible spec ( $K, v$ )
where $v$ is a function on $\operatorname{states}(K)$
The visible behaviours:
$\operatorname{Obs}(K, v)=\left\{v^{\omega}(\mathrm{xs}) \mid \mathrm{xs} \in \operatorname{Beh}(K)\right\}$
$(K, v)$ implements $(L, w)$ iff $\ldots$
$\operatorname{Obs}(K, v) \subseteq \operatorname{Obs}(L, w)$
(differs from Abadi-Lamport)
Theorem (new). ( $K, v$ ) implements ( $L, w$ )
if and only if there is a simulation $F: K \rightarrow L$
with $F \subseteq\{(x, y) \mid v(x)=w(y)\}$.

## 3. Forward Simulations

 xi$F \subseteq \operatorname{states}(K) \times \operatorname{states}(L)$
is a forward simulation iff
(F0) For every $x \in \operatorname{init}(K)$,
there is $y \in \operatorname{init}(L)$ with $(x, y) \in F$
(F1) For every $(x, y) \in F$
and every $x^{\prime}$ with $\left(x, x^{\prime}\right) \in \operatorname{step}(K)$,
there is $y^{\prime}$ with $\left(y, y^{\prime}\right) \in \operatorname{step}(L)$ and $\left(x^{\prime}, y^{\prime}\right) \in F$
(F2) Every infinite initial execution ys of $L$
with $(x s, y s) \in F^{\omega}$ for some $x s \in \operatorname{Beh}(K)$
has $y s \in \operatorname{prop}(L)$

## Theorem.

Every forward simulation is a simulation

## Example

Different Periods
Specs $K(m)$ and $K(2 \cdot m)$ as above
Relation $F$ given by

$$
(j, k) \in F \equiv k=j \quad \vee \quad k=j+m
$$

$F$ is a forward simulation $K(m) \rightarrow K(2 \cdot m)$
There is no refinement mapping from $K(m)$ to $K(2 \cdot m)$.

## Backward Simulations

$F \subseteq \operatorname{states}(K) \times \operatorname{states}(L)$
is a backward simulation (version Jonnson) iff
(B0) Every pair $(x, y) \in F$
with $x \in \operatorname{init}(K)$ has $y \in \operatorname{init}(L)$.
(B1) For every pair $\left(x^{\prime}, y^{\prime}\right) \in F$ and every $x$ with $\left(x, x^{\prime}\right) \in \operatorname{step}(K)$,
there is $y$ with $(x, y) \in F$ and $\left(y, y^{\prime}\right) \in \operatorname{step}(L)$.
(B2) Every behaviour xs of $K$ has infinitely many $n$ with $\left(\mathrm{xs}_{n} ; F\right)$ nonempty and finite.
(B3) Every infinite initial execution ys of $L$
with $(x s, y s) \in F^{\omega}$ for some $x s \in \operatorname{Beh}(K)$
has $y s \in \operatorname{prop}(L)$.
Theorem.
Every backward simulation is a simulation

## xiii.1. -

Every composition of simulations is a simulation.
A composition of forward/backward simulations need not be a forward/backward simulation.
The example with prescience is a backward simulation.
The finiteness condition in (B2) is inconvenient.
It is needed to apply König's Lemma.

## 4. Eternity Variables (new)

 xivLet $M$ be a type for an "eternity" variable $m$
A relation $R \subseteq \operatorname{states}(K) \times M$
is a behaviour restriction over $K$ $\equiv$
for every behaviour xs of $K$
there exists $m \in M$ with

$$
\left(\forall n::\left(x s_{n}, m\right) \in R\right)
$$

## Soundness of

Eternity Extension xV
Let $R$ be a behaviour restriction over $K$.
Construct spec $W$ :
$\operatorname{states}(W)=R \subseteq \operatorname{states}(K) \times M$
$\operatorname{init}(W)=R \cap(\operatorname{init}(K) \times M)$
$\operatorname{prop}(W)=\left\{\mathrm{ws} \mid \mathrm{fst}^{\omega}(\mathrm{ws}) \in \operatorname{prop}(K)\right\}$
$\left((x, m),\left(x^{\prime}, m^{\prime}\right)\right) \in \operatorname{step}(W) \equiv$

$$
\left(x, x^{\prime}\right) \in \operatorname{step}(K) \wedge m^{\prime}=m
$$

Theorem. $F=\left\{\left(x,\left(x^{\prime}, m\right)\right) \mid x=x^{\prime}\right\}$ gives a simulation $K \rightarrow W$.
Proof. Let $x s \in \operatorname{Beh}(K)$.
Choose $m \in M$ with $\left(\forall n::\left(x s_{n}, m\right) \in R\right)$.
Define $y s_{n}=\left(x s_{n}, m\right) \in R=\operatorname{states}(W)$.
Then $y s \in \operatorname{Beh}(W)$ and all $\left(x s_{n}, y s_{n}\right) \in F$.

## 5. Towards Completeness

$\qquad$ xvi
We want to write an arbitrary simulation $F$
as a composition of special ones:
forward simulations
(backward simulations)
eternity extensions
All these "preserve quiescence"
Therefore, $F$ must "preserve quiescence"

## Preservation <br> of Quiescence

$\qquad$ xvii
For $x s \in \operatorname{Beh}(K)$
the set of quiescent indices is

$$
Q_{K}(x s)=\left\{n \mid(x s \mid n)+\left(x s_{n}^{\omega}\right) \in \operatorname{Beh}(K)\right\}
$$

$F: K \rightarrow L$ preserves quiescence
$\equiv$
for every $x s \in \operatorname{Beh}(K)$
there exists ys $\in \operatorname{Beh}(L)$
with $\left(x s_{n}, y s_{n}\right) \in F$ for all $n$
and $Q_{K}(x s) \subseteq Q_{L}(y s)$.

## Quiescence

## Lost

$K$ and $L$, with state spaces $X=\{0,1,2\}$
initial set $\{1\}$
property $\diamond \square \llbracket\{0\} \rrbracket$

$$
\begin{aligned}
& \operatorname{step}(K)=1_{X} \cup\{(1,0),(0,1)\}, \\
& \operatorname{step}(L)=1_{X} \cup\{(1,0),(1,2),(2,1)\}
\end{aligned}
$$

The quiescent indices are at the zero elements
Simulation $F=\{(0,0),(0,2),(1,1)\}: K \rightarrow L$


Example: $x s=\left(1,0,0,1,0^{\omega}\right)$
corresponds to ys $=\left(1,2,2,1,0^{\omega}\right)$
Quiescence is lost where 0 becomes 2 .

## Semantic <br> Completeness

Theorem. Let $F: K \rightarrow L$ preserve quiescence.
There is a forward simulation $H: K \rightarrow K^{\#}$,
an eternity extension $E: K^{\#} \rightarrow W$,
a refinement mapping $g: W \rightarrow L$
with $(H ; E ; g) \subseteq F$.
Sketch of proof.
$K^{\#}$ is the "unfolding" of $K$ with $\operatorname{states}\left(K^{\#}\right)$ the set of stutterfree initial executions of $K$.
$R \subseteq \operatorname{states}\left(K^{\#}\right) \times \operatorname{Beh}(L)$ holds pairs (xs, ys)
with, for some $x t \in \operatorname{Beh}(K)$,

$$
x s \sqsubseteq x t \wedge(x t, y s) \in F^{\omega} \wedge Q_{K}(x t) \subseteq Q_{L}(y s)
$$

This gives eternity extension $K^{\#} \rightarrow W$.
Function $g: R \rightarrow \operatorname{states}(L)$
maps (xs, ys) to $y s_{n-1}$ where $n=\# x s$
Preservation of quiescence is needed to make $g$ a refinement mapping $W \rightarrow L$

## Comparison

This result is simpler than
the Theorem of Abadi-Lamport (1991)
with backward simulation instead of eternity extension
There the concrete specification had to be "machine-closed"

The abstract specification had to be of "finite invisible nondeterminism" and "internally continuous"

These conditions are not unreasonable but very technical
and therefore inconvenient

## Comparison

## continued

Internal continuity is replaced by preservation of quiescence

Finite invisible nondeterminism
is replaced by the condition
that $R$ be a behaviour restriction:
For every behaviour xs of $K$
there exists $m \in M$ with

$$
\left(\forall n::\left(\mathrm{xs}_{n}, m\right) \in R\right)
$$

Usually solved by "approximating" $m$

## 6. Extended Example

## Concrete specification K0

var $\mathrm{j}:$ Nat $:=0$;
do true $\rightarrow \mathrm{j}:=\mathrm{j}+1$;
$j>0 \rightarrow j:=0 ;$
od;
prop: j decreases infinitely often.
$\operatorname{states}(K 0)=\mathbb{N}$
$\operatorname{init}(K 0)=\{0\}$
$\operatorname{prop}(K 0)=\square \diamond \llbracket>\rrbracket$

$$
\begin{aligned}
& (i, j) \in \operatorname{step}(K 0) \quad \equiv \\
& j=i+1 \quad \vee \quad j=0 \quad \vee \quad j=i
\end{aligned}
$$

## Guessing

the jumping points $\qquad$ xxiii
Abstract specification K1

$$
\begin{aligned}
& \text { var } \mathrm{j}: \mathrm{Nat}:=0, \mathrm{~m}: N a t:=0 ; \\
& \text { do } \mathrm{j}<\mathrm{m} \rightarrow \mathrm{j}:=\mathrm{j}+1 ; \\
& \rrbracket \mathrm{j}=\mathrm{m} \rightarrow \mathrm{j}:=0 ; \mathrm{m}:=0 ; \\
& \mathrm{j}=0 \rightarrow \mathrm{j}:=1 ; \quad \text { choose } \mathrm{m} \geq 1 ; \\
& \text { od } ; \\
& \text { prop: }(\mathrm{j}, \mathrm{~m}) \text { changes infinitely often. } \\
& \text { states }(K 1)=\mathbb{N} \times \mathbb{N} \\
& \text { init }(K 1)=\{(0,0)\} \\
& \operatorname{prop}(K 1)=\square \diamond \llbracket \neq \rrbracket \\
& \quad\left((j, m),\left(j^{\prime}, m^{\prime}\right)\right) \in \operatorname{step}(K 1) \equiv \\
& \left(j<m \wedge j^{\prime}=j+1 \wedge m^{\prime}=m\right) \\
& \vee\left(j=m \wedge j^{\prime}=m^{\prime}=0\right) \\
& \vee\left(j=0 \wedge j^{\prime}=1 \leq m^{\prime}\right) \\
& \vee \quad\left(j^{\prime}=j \wedge m^{\prime}=m\right) .
\end{aligned}
$$

How to let $K 0$ simulate $K 1$ ?

## Adding

## History Variables

$\qquad$ xxiv
Extend K0 with history variables
n and q to obtain $K 2$

```
var \(\mathrm{j}:\) Nat \(:=0, \mathrm{n}:\) Nat \(:=0\);
    \(\mathrm{q}:\) array \(N a t\) of \(N a t:=([N a t] 0)\);
do true \(\rightarrow \mathrm{j}:=\mathrm{j}+1 ; \mathrm{q}[\mathrm{n}]:=\mathrm{q}[\mathrm{n}]+1\);
』 \(\mathrm{j}>0 \rightarrow \mathrm{j}:=0 ; \mathrm{n}:=\mathrm{n}+1\);
od ;
prop: j decreases infinitely often.
```

$F_{0,2}: K 0 \rightarrow K 2$, the converse of the projection, is a forward simulation

## Eternity Extension

$\qquad$ $\mathbf{x x v}$

Extend K2 with eternity variable m
m is an infinite array
with the behaviour restriction (!)

$$
R: \quad \mathrm{j} \leq \mathrm{m}[\mathrm{n}] \quad \wedge \quad(\forall i: 0 \leq i<\mathrm{n}: \mathrm{m}[i]=\mathrm{q}[i]) .
$$

This gives spec $K 3$ with

$$
\begin{aligned}
& \left((j, n, q, m),\left(j^{\prime}, n^{\prime}, q^{\prime}, m^{\prime}\right)\right) \in \operatorname{step}(K 3) \equiv \\
& \quad m=m^{\prime} \wedge\left((j, n, q),\left(j^{\prime}, n^{\prime}, q^{\prime}\right)\right) \in \operatorname{step}(K 2)
\end{aligned}
$$

Define $f_{3,1}: \operatorname{states}(K 3) \rightarrow \operatorname{states}(K 1)$ by

$$
f_{3,1}(j, n, q, m)=(j,(j=0 ? 0: m[n]))
$$

This is a refinement mapping $K 3 \rightarrow K 1$
We thus have $K 0 \rightarrow K 2 \rightarrow K 3 \rightarrow K 1$.

